



Part III Numerical Methods

Discretization Methods

discretization method = PDE formulation + approximating class

- finite element method (VF + FE space)

$$(FE) \quad \left[\begin{array}{l} \text{Find } u_h \in V_{h,g} = H_1^1(I) \cap \mathcal{S}_1^0(\Delta) \text{ s.t.} \\ a(u_h, v) = f(v) \quad \forall v \in V_{h,0} \end{array} \right.$$

where

$$V_{h,g} = \left\{ v \in \mathcal{S}_1^0(\Delta) \mid v|_{\Gamma_D} = g \right\}, \quad \Gamma_D \in \{a, b\}$$

the corresponding algebraic equation

$$\bullet u_h(x) = \sum_{i=1}^N u_i \varphi_i(x) \in V_h = \text{span} \left\{ \varphi_i(x) \right\}_{i=1}^N$$

$$\bullet f(v) \text{ is linear} \iff f(\alpha_1 v_1 + \alpha_2 v_2) = \alpha_1 f(v_1) + \alpha_2 f(v_2)$$

• $a(u, v)$ is bilinear $\iff a(u, v)$ is linear w.r.t. u and v .

$$(FE) \implies f(v) = a(u_h, v) \\ = \sum_{i=1}^N u_i a(\varphi_i, v) \quad \forall v \in V_h$$

$$\underset{v = \varphi_j}{\underline{f}} \quad \sum_{i=1}^N u_i a(\varphi_i, \varphi_j) = f(\varphi_j) \quad \text{for } j=1, \dots, N.$$

$$\implies \begin{matrix} A & U & = & F \\ N \times N & N \times 1 & & N \times 1 \end{matrix}$$

$$\text{where } U = (u_1, \dots, u_N)^T, \quad F = (f(\varphi_1), \dots, f(\varphi_N))^T,$$

$$A = \left(a_{ij} \right)_{N \times N} \quad \text{with } a_{ij} = a(\varphi_j, \varphi_i).$$

Questions

(1) existence, uniqueness, stability?

(2) error estimate: $\|u - u_h\|_a \leq ?$

(3) algebraic solvers?

(4) how to choose the partition Δ ?

• NN method

$$M_n = \left\{ c_0 + \sum_{i=1}^n c_i \sigma(x-b_i) \mid c_i, b_i \in \mathbb{R} \right\}$$

Properties of M_n

- (1) $n+1$ linear parameters $\{c_i\}_{i=0}^n$
 n nonlinear parameters $\{b_i\}_{i=1}^n$

- (2) Assume that $\{b_i\}_{i=1}^n$ is fixed and distinct.

Then $\{1, \sigma(x-b_1), \dots, \sigma(x-b_n)\}$ is l. indep.

Proof (Liu-Cai-Chen, CAMA 2022)

• $\{1, \sigma(x-b_1)\}$ is l. indep because $\sigma(x-b_1) \equiv 0 \forall x \in (-\infty, b_1)$

• assume $\{1, \sigma(x-b_1), \dots, \sigma(x-b_k)\}$ are l. indep.

• $c_0 + \sum_{i=1}^{k+1} c_i \sigma(x-b_i) \equiv 0 \Rightarrow c_0 + \sum_{i=1}^k c_i \sigma(x-b_i) \equiv 0 \forall x < b_{k+1} \Rightarrow c_i = 0$ #

- (3) M_n is a set but not a linear space.

Let $v_k(x) = c_0^{(k)} + \sum_i c_i^{(k)} \sigma(x-b_i^{(k)})$ for $k=1, 2$.

assume that there exists j s.t. $b_j^{(1)} \neq b_j^{(2)}$

$\Rightarrow V_1 + V_2$ has at least $n+1$ breaking pts

$\Rightarrow V_1 + V_2 \notin M_n$.

- NN-based methods

(1) based on the energy minimization formulation

deep Ritz, finite neuron, Ritz net, ...

(2) based on the least-squares formulations

PINN, LSNN, ...

least-squares neural network (LSNN) method

Find $u_n \in M_n$ s.t.

$$\mathcal{L}(u_n; f) = \min_{v \in M_n} \mathcal{L}(v; f).$$

Homework Problems

(Brenner & Scott)

Chapter 0 #2, 3, 8

#2. Derive variational formulation of BVP $\begin{cases} -u'' + u = f & \bar{\omega}(0,1) \\ u(0) = u(1) = 0. \end{cases}$

#3. Derive variational formulation of BVP $\begin{cases} -u'' = f & \bar{\omega}(0,1) \\ u'(0) = 0, u'(1) = 0 \end{cases}$

Explain why (BVP) and (VP) are not well-posed.

#8. Prove that (BVP) $\begin{cases} -u'' = f & \bar{\omega}(0,1) \\ u(0) = 0, u'(1) = 0 \end{cases}$ has a solution $u \in C^2([0,1])$ provided $f \in C^0([0,1])$.

$$\text{(Hint: } u(x) = \int_0^x \left(\int_s^1 f(t) dt \right) ds \text{)}$$

Chapter 1 #1, 3

#1. Suppose that Ω is bounded and that $1 \leq p \leq q \leq \infty$.

Prove that $L^q(\Omega) \subset L^p(\Omega)$.

#3. Suppose that Ω is bounded and that $\lim_{j \rightarrow \infty} \|f_j - f\|_{L^p(\Omega)} = 0$.

Prove $\lim_{j \rightarrow \infty} \int_{\Omega} f_j(x) dx = \int_{\Omega} f(x) dx$.

